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A Broadband Model of a Potential Transformer

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Abstract: In this paper, a broadband circuit model of a potential transformer (PT) based on fractional calculus and circuit augmentation method was proposed to improve the high frequency characteristic while providing physical significance of the existing traditional equivalent circuit model with simple structure. In order to comprehensively reflect on the characteristics of hysteresis of the iron core, a fractional model of the magnetic hysteresis loop in iron core measured by a no-load experiment was set up instead of the single-value magnetization curve of previous model. Besides, the original equivalent circuit model in the wide range of frequency. The element values were calculated by the Brune method of synthesis. For validity, comparisons between the simulation and experiment of a 10 kV single-phase oil-immersed PT with lightning overvoltage and switching overvoltage were conducted, respectively. The results showed that the broadband model presented in the paper had good accuracy while reserving the physical significance of original equivalent circuit model.

Keywords: Broadband modeling, Hysteresis, nonlinear, Network synthesis, Potential transformer.

1. INTRODUCTION

Power transformer is one of the most important and critical devices in power systems [1, 2]. There are many kinds of transformer-like devices such as generator transformer, main transformer, potential transformers (PT) and current transformers (CT), etc. Potential transformer (PT) plays an important role in the field of power system measurement and protection. Traditional equivalent circuit model with simple structure and explicit physical significance correlate merely well with the measured parameters at lower frequencies. However, it deviates at higher frequencies (e.g. lightning overvoltage and switching overvoltage), therefore, the existing models cannot meet the stringent demand of production and movement. It is of great theoretical significance and practical value to set up an accurately broadband model.

There are several kinds of potential transformer models in use since decades [3-9]. In general, there are three ways of device modeling. The first one is pure physical method based on the specific structure of the devices, which requires the details about the structure and solve the complex electromagnetic field problems. The second one is the blackbox method according to the characteristics of external ports. The third one is the gray-box method. However, the existing transformer modeling methods are only the first two, i.e. detailed model and black-box methods. On one hand, the detailed model of the transformer, valid for dozens of megahertz frequency range, requires that each turn should be represented by all mutual inductance coupling with each turn, and self-induction and self-capacitance. Solving such a model is very time-consuming. On the other hand, black-box model is a pure mathematical method which cannot reflect the physical significance of equipments. In this paper, the third one was used to establish the broadband circuit model for PT.

The iron core is a nonlinear element under the action of a large signal. There are several key factors such as magnetic saturation, hysteresis and eddy current for the nonlinear phenomena of iron core. However, it is difficult to set up a model having high accuracy for the analysis of Ferroresonant circuit. For modeling of the core excitation system, there have been some achievements since 1960. Widger proposed using a rational fraction approximation to represent the magnetization curves in 1969 [10]. Chua and Stromsmoe established the hysteresis model for electronic circuit studies in 1970 [11]. Bailey and Talukdar established the hysteresis model for power system studies in 1976 [12], and Saito et al. applied it to the simulation of single phase parallel inverter. Lucas proposed using a non-integer power series to represent the magnetization curves in 1988 [13]. Lucas et al. proposed using nonlinear inductance and nonlinear resistors in parallel connection to simulate the iron core magnetization process 1992 [14]. However, the magnetization curves of existing models are single-valued. In order to reflect the characteristics

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of the hysteresis of the iron core completely, there is a need to model the whole magnetic hysteresis loop. In this paper, a fractional order model for the magnetic hysteresis loop of iron core was established.

2. CIRCUIT AUGMENTATION METHOD

Circuit augmentation method is a gray-box method, and its basic augmentation concept is shown in Fig. (1) [9, 15, 16].

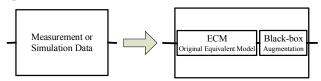
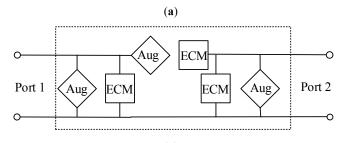
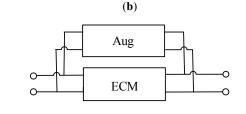


Fig. (1). Schematic of circuit augmentation method.

Among various kinds of augmentation methods, there are three common methods such as branch augmentation, parallel augmentation and cascade augmentation, as shown in Fig. (2).





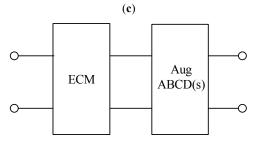


Fig. (2). Schematic of three common augmentation methods. (a) branch augmentation, (b) parallel augmentation, (c) cascade augmentation.

For m-port networks, the modified nodal analysis (MNA) equations [9, 14, 15] are shown below:

$$\mathbf{A}(j\boldsymbol{\omega})\boldsymbol{x} = \mathbf{B}\boldsymbol{v} \tag{1}$$

where $\mathbf{A}(j\omega) \in \mathbb{C}^{N \times N}$ is the MNA matrix in the frequency ω , $\mathbf{B} \in \mathbb{R}^{N \times m}$ is a selection matrix which introduces the port voltages into the node space of MNA equations and $\mathbf{B} = [0,1]^{\mathrm{T}}$, $\mathbf{v} \in \mathbb{C}^{m \times 1}$ is a column vector composed by port voltages.

$$\mathbf{x} = \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{bmatrix} \in \mathbb{C}^{N \times 1}$$
(2)

where $\mathbf{x}_1 \in \mathbb{C}^{(N-m)\times 1}$ is a column vector composed of node voltages and additional currents, and $\mathbf{x}_2 \in \mathbb{C}^{m\times 1}$ is a column vector composed of port currents.

From formula (1), the short-circuit admittance matrix of the m-port equivalent circuit is obtained.

$$\mathbf{Y} = \mathbf{B}^{\mathrm{T}} \mathbf{A}^{-1} \mathbf{B} \tag{3}$$

 \mathbf{Y}_{meas} is used to denote the measured short-circuit admittance matrix. The purpose of circuit augmentation method is to obtain modified model $\hat{\mathbf{Y}}$ such that it matches the entire broadband spectrum by adding the corresponding branches $\Delta \mathbf{Y}$, i.e. $\hat{\mathbf{Y}} = \mathbf{Y} + \Delta \mathbf{Y}$.

Then, the following error function is obtained:

$$\varepsilon(j\omega) = \left\| \mathbf{Y}_{meas}(j\omega) - \hat{\mathbf{Y}}(j\omega) \right\|$$

= $\left\| \mathbf{Y}_{meas}(j\omega) - \mathbf{B}^{\mathrm{T}} \mathbf{A}^{-1} \mathbf{B} - \Delta \mathbf{Y}(j\omega) \right\|$ (4)

In this paper, the Y_{meas} parameters could also be indirectly deduced with scatting parameters S_{meas} measured by Agilent 4395A working as network analyzer, as shown in Fig. (3), and the measurement range of frequency with 87512A was from DC to 2 GHz.

According to the two-port theory, the Y_{meas} parameter matrix of PT/CT can be obtained from the S_{meas} .

$$Y = \begin{bmatrix} Y_{11} & Y_{12} \\ Y_{21} & Y_{22} \end{bmatrix} = \begin{bmatrix} R(\mathbf{E} + \mathbf{S}) \end{bmatrix}^{-1} (\mathbf{E} - \mathbf{S})$$

$$= \frac{1}{Z_0} \frac{1}{(1 + S_{11})(1 + S_{22}) - S_{12}S_{21}} \times$$
(5)
$$\begin{bmatrix} (1 - S_{11})(1 + S_{22}) + S_{12}S_{21} & -2S_{12} \\ -2S_{21} & (1 + S_{11})(1 - S_{22}) + S_{12}S_{21} \end{bmatrix}$$

3. ORIGINAL EQUIVALENT MODEL OF PT

A JDJ-10 of 10 kV single-phase oil-immersed PT was calculated and measured.

The iron core of electromagnetic voltage transformer is a typical nonlinear element operating under overvoltage or lightning overvoltage. Firstly, a fractional order model of iron core was established in the large signals. Experimental principles are shown in Fig. (4), where the primary side of PT is disconnected.

According to the law of electromagnetic induction and transformation ratio of PT, following relation is obtained:

$$\Psi = \int_0^t u \, dt + C \,, \ \dot{\Psi} = \frac{U}{j\omega} \text{ and } i_1 = u_2 / n_{u_2} / n$$
 (6)

And the relationship between current and flux linkage can be calculated by experimental results.

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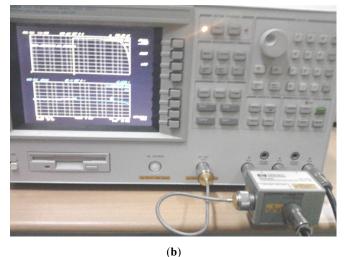




Fig. (3). Measuring equipments. (a) Agilent 4395A Analyzer, (b) 87512A.

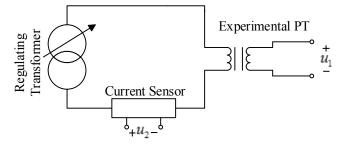


Fig. (4). No-load measurement of PT.

The basic principle describing the relationship between input and output in dynamic systems is as follows:

$$y(t) + b_1 \frac{d^{\beta_1}}{dt^{\beta_1}} y(t) + \dots + b_n \frac{d^{\beta_n}}{dt^{\beta_n}} y(t)$$

= $a_0 x(t) + a_1 \frac{d^{\alpha_1}}{dt^{\alpha_1}} x(t) + \dots + a_m \frac{d^{\alpha_m}}{dt^{\alpha_m}} x(t)$ (7)

After that the fractional polynomial of formula (8) was used to fit into the hysteresis loop

$$B = a_0 H + \sum_{k=1}^{N} a_k D^{\alpha_k} H \tag{8}$$

Where
$$D^{\alpha}H = \frac{d^{\alpha}H}{dt^{\alpha}}$$
, $0 < \alpha < 1$.
Combined with $B = \frac{k}{NS} \int u \, dt$, $H = \frac{Ni}{Lk}$, $u = \frac{d\lambda}{dt}$, the

fitting result of flux linkage and current was obtained.

$$u = a_0 \frac{di}{dt} + a_1 \frac{d^{1+\alpha_1}i}{dt^{1+\alpha_1}} + a_2 \frac{d^{1+\alpha_2}i}{dt^{1+\alpha_2}} + \dots + a_6 \frac{d^{1+\alpha_6}i}{dt^{1+\alpha_6}}$$
(9)

The circuit is shown in Fig. (5), and for the sake of brevity, Fig. (6) was used. Results of comparison between measurement and simulation are shown in Fig. (7). In addition, the values of coefficient a_i and their correspondent α_i are shown in Table 1.



Fig. (5). Equivalent circuit of iron core.





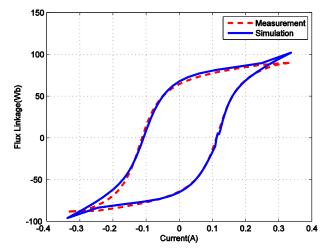


Fig. (7). Comparison result between measurement and simulation.

Using the Agilent 4395A Analyzer, the scattering parameters (S) were obtained, as shown in Fig. (8), and the transfer characteristic of PT is shown in Fig. (9).

At low frequency, the leakage inductance and resistance play a leading role. Because the signal of Agilent 4395A Analyzer was small-signal input, therefore the characteristic of the core was observed to be linear and the low frequency model of PT/two-winding transformer is shown in Fig. (10).

Table 1. Coefficients and orders.

Coefficient	Order	
$a_0 = -0.00245393050655755$	null	
$a_1 = -3.60492387516746$	$\alpha_1 = 0.076804$	
$a_2 = -0.791579409744237$	$\alpha_2 = 0.23351$	
a ₃ =1.87912230687602	α ₃ =0.47205	
a_4 =0.701165866198962	$\alpha_4 = 0.53542$	
$a_5 = -0.253480210360523$	$\alpha_5 = 0.59612$	
$a_6 = 0.0440853220991656$	$\alpha_6 = 0.64206$	

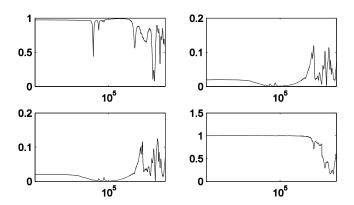


Fig. (8). Scattering parameters of PT.

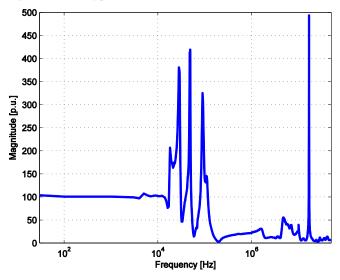


Fig. (9). Transfer characteristic of PT.

Therefore, the equivalent circuit in primary side can be calculated by

$$Z_{11} - Z_{12} = R_1 + j\omega L_1$$
 and $Z_{22} - Z_{12} = n^2 (R_2 + j\omega L_2)$ (10)

At medium frequency (≤ 100 kHZ), the equivalent circuit model of PT/two-winding transformer can be shown in Fig. (11).

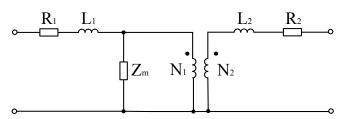


Fig. (10). Low frequency model of PT/two-winding transformer.

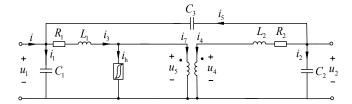


Fig. (11). Medium frequency model of PT/two-winding transformer.

Y is the admittance matrix, as shown in formula (11)

$$\mathbf{Y} = \begin{bmatrix} A_{22}B_{11} - A_{12}B_{21} & A_{22}B_{12} - A_{12}B_{22} \\ -A_{21}B_{11} + A_{11}B_{21} & -A_{21}B_{12} + A_{11}B_{22} \end{bmatrix}$$
(11)

Where $A_{11} = j\omega(L_1 + Z_m + R_1)$, $A_{12} = j\omega Z_m$, $A_{21} = j\omega Z_m$, $A_{22} = j\omega(n^2 L_2 + Z_m + n^2 R_2)$,

$$\begin{split} B_{11} &= 1 - \omega^2 \Big[C_3 \big(L_1 + R_1 \big) + C_1 \big(L_1 + R_1 + Z_m \big) \Big] &, \\ B_{12} &= \omega^2 \Big[C_3 \big(L_1 + R_1 \big) - Z_m \cdot C_2 \Big], \\ B_{21} &= \omega^2 \Big[C_3 \big(n^2 L_2 + n^2 R_2 \big) - Z_m \cdot C_1 \Big] &, \\ B_{22} &= 1 - \omega^2 \Big[C_3 \big(n^2 L_2 + n^2 R_2 \big) + C_2 \big(n^2 L_2 + n^2 R_2 + Z_m \big) \Big]. \end{split}$$

Spurious capacitors can be calculated by formula (11).

Finally, the optimized element values were obtained with particle swarm optimization. The components of original equivalent circuit model were $C_1 = 0.15 \times 10^{-9}$ F, $C_2 = 3.6607 \times 10^{-13}$ F, $C_3 = 0.89 \times 10^{-2}$ F, $R_1 = 1.6271\Omega$, $R_2 = 0.00126\Omega$, $L_1 = 3.5272$ H, and $L_2 = 0.0089$ H, r.

4. AUGMENTATION BRANCHES

The spurious capacitors shown in Fig. (11) can be regarded as demonstrating a delta connection and meanwhile the rest shown in Fig. (11) can be regarded as a star connection scheme. Using the star-delta switching, the spurious capacitors were simplified into rest. The original equivalent circuit model and its augmentation considered in this paper are shown in Fig. (12).

 \mathbf{Y}_{Aug1} , \mathbf{Y}_{Aug2} and \mathbf{Y}_{Aug3} can be calculated by the shortcircuit admittance $\mathbf{Y} = \begin{bmatrix} Y_{11} & Y_{12} \\ Y_{21} & Y_{22} \end{bmatrix}$ of original equivalent circuit model, as shown in formula (12)

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$$\begin{cases} Y_{aug1}(\omega_n) = Y_{11.meas}(\omega_n) + Y_{21.meas}(\omega_n) - Y_{11.ecm}(\omega_n) - Y_{21.ecm}(\omega_n) \\ Y_{aug2}(\omega_n) = Y_{12.meas}(\omega_n) - Y_{12.ecm}(\omega_n) \\ Y_{aug3}(\omega_n) = Y_{22.meas}(\omega_n) + Y_{12.meas}(\omega_n) - Y_{22.ecm}(\omega_n) - Y_{12.ecm}(\omega_n) \\ \hline Y_{aug3}(\omega_n) = Y_{22.meas}(\omega_n) + Y_{12.meas}(\omega_n) - Y_{22.ecm}(\omega_n) - Y_{12.ecm}(\omega_n) \\ \hline Y_{aug3}(\omega_n) = Y_{22.meas}(\omega_n) + Y_{12.meas}(\omega_n) - Y_{22.ecm}(\omega_n) - Y_{12.ecm}(\omega_n) \\ \hline Y_{aug3}(\omega_n) = Y_{22.meas}(\omega_n) + Y_{12.meas}(\omega_n) - Y_{22.ecm}(\omega_n) - Y_{12.ecm}(\omega_n) \\ \hline Y_{aug3}(\omega_n) = Y_{22.meas}(\omega_n) + Y_{12.meas}(\omega_n) - Y_{22.ecm}(\omega_n) - Y_{12.ecm}(\omega_n) \\ \hline Y_{aug3}(\omega_n) = Y_{22.meas}(\omega_n) + Y_{12.meas}(\omega_n) - Y_{22.ecm}(\omega_n) - Y_{12.ecm}(\omega_n) \\ \hline Y_{aug3}(\omega_n) = Y_{22.meas}(\omega_n) + Y_{12.meas}(\omega_n) - Y_{22.ecm}(\omega_n) - Y_{12.ecm}(\omega_n) \\ \hline Y_{aug3}(\omega_n) = Y_{22.meas}(\omega_n) + Y_{12.meas}(\omega_n) - Y_{22.ecm}(\omega_n) - Y_{12.ecm}(\omega_n) \\ \hline Y_{aug3}(\omega_n) = Y_{22.meas}(\omega_n) + Y_{12.meas}(\omega_n) - Y_{22.ecm}(\omega_n) - Y_{12.ecm}(\omega_n) \\ \hline Y_{aug3}(\omega_n) = Y_{22.meas}(\omega_n) + Y_{12.meas}(\omega_n) - Y_{22.ecm}(\omega_n) - Y_{12.ecm}(\omega_n) \\ \hline Y_{aug3}(\omega_n) = Y_{22.meas}(\omega_n) + Y_{12.meas}(\omega_n) - Y_{22.ecm}(\omega_n) - Y_{12.ecm}(\omega_n) \\ \hline Y_{aug3}(\omega_n) = Y_{22.meas}(\omega_n) + Y_{22.meas}(\omega_n) - Y_{22.ecm}(\omega_n) - Y_{22.ecm}(\omega_n) \\ \hline Y_{aug3}(\omega_n) = Y_{22.meas}(\omega_n) + Y_{22.meas}(\omega_n) - Y_{22.ecm}(\omega_n) - Y_{22.ecm}(\omega_n) - Y_{22.ecm}(\omega_n) - Y_{22.ecm}(\omega_n) - Y_{22.ecm}(\omega_n) \\ \hline Y_{aug3}(\omega_n) = Y_{22.meas}(\omega_n) + Y_{22.meas}(\omega_n) - Y_{22.ecm}(\omega_n) - Y$$

Fig. (12). The original equivalent circuit model and its augmentation .

Table 2. Element values of brune realizations in Y_{Aug1} .

The Y_{Aug} can be expressed by the following rational fractional function

$$Y_{Aug}(s) = \sum_{i=1}^{Q} \frac{k_i}{s - p_i} + d + se$$
(13)

Then the CAM model $Y_{cam}(s)$ with Y_{Aug} was obtained as shown below:

$$Y_{cam}(s) = Y_{ecm}(s) + Y_{Aug}(s)$$

= $Y_{ecm}(s) + \sum_{i=1}^{Q} \frac{k_i}{s - p_i} + d + se$ (14)

Using the vector fitting technology [22], the formula (13) was obtained. Following this, , the Brune method of synthesis [17, 18] was executed using the formula (13), to make passivity correction before network synthesis if necessary. In this paper, the element values of Brune realizations are shown in Tables **2-4**.

Element Order Number	R_i (Ohm)	L_{pi} (H)	<i>L</i> _{si} (H)	$C_i(\mathbf{F})$
1	null	null	null	3.63674300e-11
2	1.266848967	3.69518403e-5	5.66089730e-5	1.28305786e-11
3	1.878957500e+2	Null	null	4.04340177e-11
4	4.396677378e+2	4.57558350e-6	5.17399620e-6	1.03299110e-11
5	4.635046485e+1	1.90412390e-5	4.03330910e-4	2.63177329e-11
6	2.169917945e+1	2.67160370e-4	2.66012790e-4	3.48479594e-13
7	4.584115244e+1	6.43917540e-4	6.55973110e-4	3.21056683e-13
8	4.181628600e+2	2.86914197e-1	1.67583400e-2	4.02803017e-9
9	3.271638000e+2	1.21779058e-5	5.93108426e-6	8.67269309e-12
10	9.050521138e+1	1.30438753e-6	8.64927476e-7	3.544449687e-11
11	4.141604960e+1	null	null	8.35087727e-10

Table 3. Element values of brune realizations in Y_{Aug2} .

Element Order Number	<i>R_i</i> (Ohm)	$L_{pi}\left(\mathrm{H} ight)$	<i>L</i> _{si} (H)	$C_i(\mathbf{F})$
1	null	null	null	4.2215000100e-12
2	2.0595917846e+1	3.3077103907e-5	6.3022277009e-5	1.7323021385e-12
3	4.4536451181e+1	8.0784349644e-4	2.0938785210e-3	6.318000000e-12
4	5.9765143964e+1	1.4388813239e-4	1.4312993211e-4	3.7443352352e-13
5	9.8766379800e+2	2.3113554230e-3	2.6686902690e-3	7.4471784533e-14
6	4.1011033900e+2	1.7646411941e-4	1.3081257294e-4	3.2111664597e-12
7	9.3037759100e+2	1.1106565872e-4	8.8615102760e-5	9.6379891693e-13
8	4.4236771300e+2	3.6690638190e-5	1.0851617050e-3	3.8613043587e-12
9	1.0939862600e+3	1.2038336188	1.4828517968	6.5019597701e-12
10	6.6173770900e+2	4.4739023715	6.1202025241	2.0319866132e-11
11	1.5112170100e+4	1.1934188199	1.3377369747	1.8605827939e-11
12	2.9523395100e+5	null	null	Null

Element Order Number	R _i (Ohm)	<i>L</i> _{pi} (H)	L_{si} (H)	$C_i(\mathbf{F})$
1	null	null	null	4.2474e-11
2	3.1335651795	6.7709594892e-7	1.9030792845e-9	4.0357132918e-11
3	1.4401582442e+1	3.1207076637e-6	6.6375024751e-6	2.4301491549e-10
4	1.2293092322e+1	2.2531121967e-5	1.7856286542e-5	2.0674057040e-11
5	2.1524401051e+1	2.7444836467e-6	3.4431675710e-6	2.4366301323e-11
6	4.1562742265e+1	4.0200331066e-5	2.5002152079e-4	1.1044082653e-10
7	2.6632473052e+1	1.2490307208e-2	1.3977427258e-2	5.8451130705e-9
8	1.1838633300e+2	4.9273501618e+1	4.9319208496e+1	4.8469844710e-12
9	3.2251066100e+2	7.9322289490e-7	3.6116798504e-6	1.4675768409e-11
10	2.1537725300e+2	2.5982499172e-2	2.8122929728e-2	8.5752843932e-10
11	2.5765621300e+3	6.1225428800e-3	null	Null
12	1.1412753400e+4	1.5921567481e-1	1.5921593719e-1	5.4396256477e-21
13	3.6104573900e+4	Null	null	2.7316470209e-10

Table 4. Element Values of Brune Realizations in Y_{Aug3} .

Furthermore, the global perturbed optimization [19-21] was achieved using PSpice, and the principle is shown in formula (15)

$$Y_{cam}(s) = \sum_{\substack{i=1\\ \text{Disturbance Original Part}}}^{Q_{cam}} \frac{\tilde{k}_i + \nabla \tilde{k}_i}{s - (\tilde{p}_i + \Delta \tilde{p}_i)} + (\tilde{d} + \Delta \tilde{d}) + \sum_{\substack{i=1\\ \text{Augmentation Part}}}^{Q_{amg}} \frac{\hat{k}_i}{s - \hat{p}_i} + \hat{d}$$
(15)

5. EXPERIMENTAL RESULTS

The PT with lightning overvoltage and switching overvoltage were measured followed by comparison of the simulation result. The lightning overvoltage waveform is shown in Fig. (13), and the switching overvoltage is shown in Fig. (14).

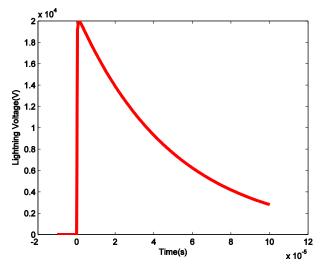


Fig. (13). Lightning overvoltage waveform.

As shown in Figs. (15, 16), through the comparison of measurement and simulation, the accuracy was observed to be satisfactory.

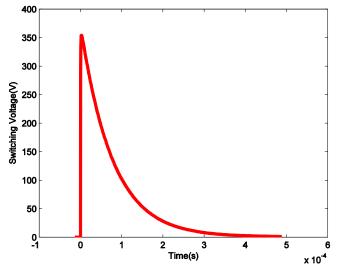


Fig. (14). Switching overvoltage waveform.

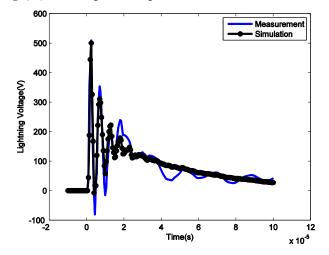


Fig. (15). Comparison under lightning overvoltage.

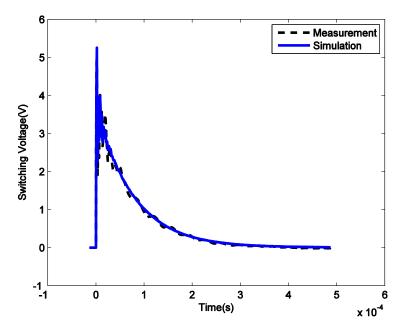


Fig. (16). Comparison under switching overvoltage.

CONCLUSION

In this paper, a broadband circuit model of PT was proposed for the power system measurement and protection in a wide range of frequencies. According to the no-load experiment data, the hysteresis loop curve was obtained to establish a fractional order model for the iron core of PT. Moreover, according to the S parameters measured by the Agilent 4395A analyzer with 87512A, the element's values were calculated using circuit augmentation method and Brune realization of synthesis for the augmented parts of PT.

To verify the performance of the proposed broadband model of the PT, experiments of lightning overvoltage and switching overvoltage were conducted. A good agreement was obtained between simulation and measurement under the lightning overvoltage and switching overvoltage respectively, and the results show that the proposed method enabled the engineers to retain the original equivalent circuit models while providing physical significance to obtain the high frequency characteristic accurately.

CONFLICT OF INTEREST

The authors confirm that this article content has no conflict of interest.

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